# Linear Regresion 

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## 1 Linear regresion

This is modeled after Morten Hjorth-Jensen https://compphysics.github.io/ MachineLearning/doc/web/course.html Please see his lecture notes and get deeper into Machine Learning.
Linear regresion is a low level (or first step in) machine learning (ML), but all equations can be derived analytically and important concepts for ML can be introduced, such as, the choice of model, assumptions of error, cost function, regularizations, correlations, etc.

Some of the important concepts are:

- Data input and output, which we will denote by $D$ :

$$
\begin{equation*}
D=\left\{\left(x_{0}, y_{0}\right),\left(x_{1}, y_{1}\right), \ldots\left(x_{n-1}, y_{n-1}\right)\right\} \tag{1}
\end{equation*}
$$

Here $x_{i}$ is the input and $y_{i}$ is the onput. $x_{i}$ can be scalar or large vector of data. Similarly, $y_{i}$ might be a number, or, classification.

Examples: i) credit card information for customers: $x_{i}$ is the amount of loan, the income, the marriage status, etc. The ouput is the prediction that the customer will default, i.e., true/false. ii) handwriting recognition: The input $x_{i}$ are the pixels of the image, the output is a number or a letter. iii) cancer data: The input $x_{i}$ are characteristics of the tumor such as its size, radius, smoothness, symmetry, fractal dimension, etc., the output is $M=$ malignant, $B=$ benign.

- Model: basic assumption about the data to be fit.

For linear regression we assume that the data can be fit with continuous function $\tilde{y}(x)$, which is deterministic, and the data has some extra random noise, normally distributed, i.e.,

$$
y_{i}=\tilde{y}\left(x_{i}\right)+\varepsilon_{i}
$$

where $\tilde{y}(x)$ can be expanded in terms of some continuous functions, and $\varepsilon=\eta N\left(0, \sigma^{2}\right)$, where $\eta$ is some small number, and $N$ is normal (gaussian) distribution with vanishing mean and width $\sigma$.

- Cost function (functional to be minimized):

The simplest is the mean average error (MAE), which is equivalent to $\chi^{2}$ :

$$
C=\frac{1}{n} \sum_{i}\left(\tilde{y}\left(x_{i}\right)-y_{i}\right)^{2}
$$

but different cost functions, such as Ridge regression and Lasso regression are often used.
The cross-entropy is used for binary models (discrete with two outcomes):

$$
C=\sum_{i} y_{i} \log \left(p\left(y_{i}=1 \mid x_{i}\right)\right)+\left(1-y_{i}\right) \log \left(1-p\left(y_{i}=1 \mid x_{i}\right)\right)
$$

- Covariance and Correlation matrix: It meassures correlation between different features in data. It can be used to eliminate irrelevant parameters from the model or those that are almost linearly dependent.
The covariance $\operatorname{cov}\left(\vec{x}_{i}, \vec{x}_{j}\right)$ is defined for two vectors that have many components $\vec{x}_{i}=x_{n, i}$ and $\vec{x}_{j}=x_{n, j}$ and takes the form

$$
\begin{align*}
& \operatorname{cov}\left(\vec{x}_{i}, \vec{x}_{j}\right)=\frac{1}{n} \sum_{n}\left(x_{n, i}-<x_{i}>\right)\left(x_{n, j}-<x_{j}>\right)  \tag{2}\\
& <x_{i}>=\frac{1}{n} \sum_{n} x_{n, i} \tag{3}
\end{align*}
$$

The diagonal parts of the covariance is the variance, i.e.,

$$
\begin{equation*}
\operatorname{cov}\left(\vec{x}_{i}, \vec{x}_{i}\right) \equiv \sigma_{i}^{2}=\frac{1}{n} \sum_{n}\left(x_{n, i}-<x_{i}>\right)^{2} \tag{5}
\end{equation*}
$$

which can be "taken out" of covariance matrix to define correlation matrix. The matrix elements of the correlation matrix are simply given by

$$
\begin{align*}
\operatorname{corr}\left(\vec{x}_{i}, \vec{x}_{j}\right) & =\frac{\operatorname{cov}\left(\vec{x}_{i}, \vec{x}_{j}\right)}{\sqrt{\operatorname{cov}\left(\vec{x}_{i}, \vec{x}_{i}\right) \operatorname{cov}\left(\vec{x}_{j}, \vec{x}_{j}\right)}}  \tag{6}\\
\operatorname{corr}\left(\vec{x}_{i}, \vec{x}_{j}\right) & =\frac{1}{\sigma_{i} \sigma_{j}} \frac{1}{n} \sum_{n}\left(x_{n, i}-<x_{i}>\right)\left(x_{n, j}-<x_{j}>\right) \tag{7}
\end{align*}
$$

### 1.0.1 Linear regression details

In linear regression we try to represent the continuous function $\tilde{y}(x)$ as a linear superposition of known functions $g_{j}(x)$ with $j \in[0, \ldots p-1]$. We want to find the coefficients $\beta_{j}$ of the linear superposition, i.e.,

$$
\begin{equation*}
\tilde{y}\left(x_{i}\right)=\sum_{j=0}^{p-1} g_{j}\left(x_{i}\right) \beta_{j} \tag{9}
\end{equation*}
$$

The functions $g_{j}(x)$ can be a polynomial $g_{j}(x)=x^{j}$ or the Fourier components $g_{j}(x)=e^{2 \pi j x}$ or Legendre, Chebyshev polynomials, or any other complete set of functions.

Next we define the Design matrix $\mathbf{X}$, which is a rectangular matrix with $\mathbb{R}^{n \times p}$, where $n$ is the dimension of the input data components, and $p$ is the number of functions we will use in the expansion

$$
\mathbf{X}=\left[\begin{array}{cccc}
g_{0}\left(x_{0}\right) & g_{1}\left(x_{0}\right) & \cdots & g_{p-1}\left(x_{0}\right)  \tag{10}\\
g_{0}\left(x_{1}\right) & g_{1}\left(x_{1}\right) & \cdots & g_{p-1}\left(x_{1}\right) \\
\cdots & & & \\
g_{0}\left(x_{n-1}\right) & g_{1}\left(x_{n-1}\right) & \cdots & g_{p-1}\left(x_{n-1}\right)
\end{array}\right]
$$

Normaly we expect $n<p$ so that data is not overfitted.
We also define the vector of unknown parameters $\beta^{T}=\left[\beta_{0}, \beta_{1}, \ldots \beta_{p-1}\right]$ and in terms of the two, we can write a matrix equation

$$
\begin{equation*}
\tilde{y}=\mathbf{X} \beta \tag{11}
\end{equation*}
$$

The design matrix contains the complexity of the model, and is defined solely by the input data and the choice of the model. The model is linear in the unknown parameters $\beta$, hence linear regression. The cost function $C$ for the model will gives us the quality of the fit. It is now a funcion of the unknown parameters

$$
\begin{equation*}
C(\beta)=\frac{1}{n} \sum_{i=0}^{n-1}\left(y_{i}-\tilde{y}\left(x_{i}\right)\right)^{2}=\frac{1}{n} \sum_{i=0}^{n-1}\left(y_{i}-(\mathbf{X} \beta)_{i}\right)^{2} \tag{12}
\end{equation*}
$$

and should be minimized, i.e., $\frac{\partial C(\beta)}{\partial \beta}=0$. When the minimum is reached, we obtain the optimized parameters, which we will call $\beta^{*}=\min C(\beta), \beta \in \mathbb{R}^{p}$.

The derivative

$$
\frac{\partial C(\beta)}{\partial \beta}
$$

can readily be obtained

$$
\begin{equation*}
\frac{\partial C(\beta)}{\partial \beta_{l}}=\frac{\partial}{\partial \beta_{l}} \frac{1}{n} \sum_{i=0}^{n-1}\left(y_{i}-X_{i j} \beta_{j}\right)^{2} \tag{13}
\end{equation*}
$$

Here we use Einstein notation in which the sum over the repeated indices is assumed.

$$
\begin{equation*}
\frac{\partial C(\beta)}{\partial \beta_{l}}=\frac{1}{n} \sum_{i} 2\left(y_{i}-X_{i j} \beta_{j}\right)(-1) X_{i l}=-2 \frac{1}{n}\left(\mathbf{X}^{T}(y-\mathbf{X} \beta)\right)_{l} \tag{14}
\end{equation*}
$$

The minimum is reached at $\frac{\partial C(\beta)}{\partial \beta}=0$ :

$$
\begin{equation*}
\mathbf{X}^{T} y=\mathbf{X}^{T} \mathbf{X} \beta^{*} \tag{15}
\end{equation*}
$$

or

$$
\begin{equation*}
\beta^{*}=\left(\mathbf{X}^{T} \mathbf{X}\right)^{-1} \mathbf{X}^{T} y \tag{16}
\end{equation*}
$$

and therefore optimal $\tilde{y}$ is

$$
\begin{equation*}
\tilde{y}=\mathbf{X} \beta^{*}=\mathbf{X}\left(\mathbf{X}^{T} \mathbf{X}\right)^{-1} \mathbf{X}^{T} y \tag{17}
\end{equation*}
$$

The last equation says that the optimal model is given by the projection of data $y$ into a space spanned by functions $g_{j}\left(x_{i}\right)$ as encoded in design matrix $\mathbf{X}$.
One can readily check that $\mathbf{X}\left(\mathbf{X}^{T} \mathbf{X}\right)^{-1} \mathbf{X}^{T}$ has the property of a projector $P^{2}=P$.
How do we know this is minimum? We compute the second derivative, and determine its sign. The second derivative is

$$
\begin{equation*}
\frac{\partial^{2} C(\beta)}{\partial \beta_{j} \partial \beta_{l}}=\frac{\partial}{\partial \beta_{j}} \frac{1}{n} \sum_{i} 2\left(y_{i}-X_{i j} \beta_{j}\right)(-1) X_{i l}=\frac{2}{n} \sum_{i} X_{i j} X_{i l}=\frac{2}{n}\left(\mathbf{X}^{T} \mathbf{X}\right)_{j l} \tag{18}
\end{equation*}
$$

We will show thet $\mathbf{X}^{T} \mathbf{X}$ is positive definite matrix, hence, $C\left(\beta^{*}\right)$ is a global minimum.
If functions $g_{j}(x)$ are linearly dependent (or features in ML are linearly dependent) the design matrix $X$ can be singular, and $\operatorname{Det}\left(\mathbf{X}^{T} \mathbf{X}\right)=0$. In that case the inversion of this matrix is not possible, and we need to either * perform a pseudo-inverse, or, * regularize the cost function.
If $\operatorname{Det}\left(\mathbf{X}^{T} \mathbf{X}\right)=0$ we can still use SVD decomposion to inverse the matrix. This is called pseudoinverse, as the real inverse does not exist.

If matrix is singular or is non-quadratic matrix, we can still define pseudo-inverse $A^{+}$, such that $A A^{+} A=A$ and $A^{+} A A^{+}=A^{+}$, where $A A^{+}$and $A^{+} A$ is Hermitian, but is not identity matrix. This pseudoinverse is achieved by SVD.

For any matrix (quadratic or non-quadratic), the following decomposition exists:

$$
\mathbf{X}=U \sigma V^{\dagger}
$$

where $U$ and $V$ are unitary matrices $\left(U^{\dagger} U=1\right.$ and $\left.V^{\dagger} V=1\right)$, and $\sigma$ is diagonal matrix with real singular values on diagonal. If $\mathbf{X} \in \mathbb{R}^{n \times p}$ then $U \in \mathbb{R}^{n \times n}$ and $V \in \mathbb{R}^{p \times p}$ and $\sigma$ is rectangular matrix with $\min (n, p)$ values.

Next we use SVD for Design matrix $\mathbf{X}$ to obtain

$$
\mathbf{X}=U \sigma V^{T}
$$

and therefore

$$
\mathbf{X}^{T}=V \sigma U^{T}
$$

Note that the number of singular values is $p<n$. We than have

$$
\mathbf{X}^{T} \mathbf{X}=V \sigma U^{T} U \sigma V^{T}=V \sigma^{2} V^{T}
$$

and now the pseudo-inverse of this matrix is

$$
\left(\mathbf{X}^{T} \mathbf{X}\right)^{-1}=V \frac{1}{\sigma^{2}} V^{T}
$$

where the singular values that vanish are omitted.

We also point out that

$$
\mathbf{X}^{T} \mathbf{X} V=V \sigma^{2}
$$

which shows that $V$ are eigenvectors of matrix $\mathbf{X}^{T} \mathbf{X}$ and $\sigma^{2}$ are eigenvalues of the same matrix. Since $\sigma \in \mathbb{R}$ therefore $\sigma^{2} \geq 0$. We just proved previous claim that the second derivative of the cost function is positive and hence $\beta^{*}$ is a global minimum. Namely

$$
\frac{\partial^{2} C(\beta)}{\partial \beta_{j} \partial \beta_{l}}=\frac{2}{n}\left(\mathbf{X}^{T} \mathbf{X}\right)_{j l}=\frac{2}{n}\left(V \sigma^{2} V^{T}\right)_{j l}
$$

is positive definite matrix because all eigenvalues are positive.
Finally, we also express $\beta^{*}$ and $\tilde{y}$ in terms of singular values $\sigma$,

$$
\beta^{*}=\left(\mathbf{X}^{T} \mathbf{X}\right)^{-1} \mathbf{X}^{T} y=V \frac{1}{\sigma} U^{T} y
$$

and

$$
\tilde{\mathbf{y}}_{i}=(\mathbf{X} \beta)_{i}=\sum_{l, \sigma_{l}>0} U_{i l} U_{l j}^{T} y_{j} .
$$

Note that $U U^{T}=1$, but the sum above runs only over components for which $\sigma_{l}>0$, hence $\sum_{l}^{\prime} U_{i l} U_{l j}^{T}$ above is a projection and not unity. Only if $X$ is a square non-singular matrix than $\sum_{l}^{\prime} U_{i l} U_{l j}^{T}$ is unity and $\tilde{y}=y$.
As mentioned above, different types of cost functions exist, which regularize the singularity of $\mathbf{X}^{T} X$ in different ways. The most famous are Ridge regression and Lasso regression.
In Ridge regression we add lagrange multiplayer $\lambda$ such that $\sum_{j} \beta_{j}^{2}$ (or equivalently $\|\beta\|_{2}^{2}$ ) does not explode. At the same time, it also regularizes the inverse, and hence allows one to avoid pseudo-inverse.
The Ridge cost function is

$$
C(\beta)=\frac{1}{n} \sum_{i=0}^{n-1}\left(y_{i}-\tilde{y}_{i}\right)^{2}+\lambda \frac{1}{n} \sum_{j=0}^{p-1} \beta_{j}^{2}
$$

which is a constrained optimization that requires $\|\beta\|_{2}^{2}$ to be as small as possible $(\lambda>0)$, hence the purpose of such regularization is to prohibit the parameters $\beta$ to become too large. In ML we typically not optimize $C$ with respect to $\lambda$, but we rather keep it is hyperparameter, which is another parameter of the model that allows one to tune the model to best describe the data.

We can take the derivative of the cost function as before, to obtain

$$
\begin{equation*}
\frac{\partial C(\beta)}{\partial \beta_{l}}=\frac{1}{n} \sum_{i} 2\left(y_{i}-X_{i j} \beta_{j}\right)(-1) X_{i l}+\frac{2}{n} \lambda \beta_{l}=2 \frac{1}{n}\left(\mathbf{X}^{T}(\mathbf{X} \beta-y)+\lambda \beta\right)_{l} \tag{19}
\end{equation*}
$$

which has a minimum at

$$
\left(\mathbf{X}^{T} \mathbf{X}+\lambda\right) \beta^{*}=\mathbf{X}^{T} y
$$

or

$$
\beta^{*}=\left(\mathbf{X}^{T} \mathbf{X}+\lambda\right)^{-1} \mathbf{X}^{T} y
$$

which clearly avoids singularity of the inverse $\mathbf{X}^{T} \mathbf{X}$ because $\lambda>0$ and $\mathbf{X}^{T} \mathbf{X}$ is positive definite matrix.

The parameter $\lambda$ is also called shrinkage parameter, because it removes singular values which are small, i.e., removes less important degrees of freeedom.
To see that, we use SVD decomposition of $\mathbf{X}=U \sigma V^{T}$ as before, and we see that $\mathbf{X}^{T} \mathbf{X}+\lambda=$ $V\left(\sigma^{2}+\lambda\right) V^{T}$, hence

$$
\beta_{\text {Ridge }}^{*}=\left(\mathbf{X}^{T} \mathbf{X}+\lambda\right)^{-1} \mathbf{X}^{T} y=V \frac{1}{\sigma^{2}+\lambda} V^{T} V \sigma U^{T} y=V \frac{\sigma}{\sigma^{2}+\lambda} U^{T} y
$$

hence when compared to regular linear regression, Ridge regression replaces

$$
\frac{1}{\sigma} \rightarrow \frac{\sigma}{\sigma^{2}+\lambda}
$$

which essentially removes singular values which are much smaller than $\lambda$, i.e., we keep only singular values which are comparable or larger than $\lambda$ in the final result, shrinking the set of parameters $\beta$.

Another type of regression is called Lasso regression, which adds absolute values of parameters $\beta$ to cost function, i.e.,

$$
C(\beta)=\frac{1}{n} \sum_{i=0}^{n-1}\left(y_{i}-\tilde{y}_{i}\right)^{2}+\lambda \frac{1}{n} \sum_{j=0}^{p-1}\left|\beta_{j}\right|
$$

which gives derivative

$$
\begin{equation*}
\frac{\partial C(\beta)}{\partial \beta_{l}}=\frac{1}{n} \sum_{i} 2\left(y_{i}-X_{i j} \beta_{j}\right)(-1) X_{i l}+\frac{1}{n} \lambda \operatorname{sign}\left(\beta_{l}\right)=2 \frac{1}{n}\left(\mathbf{X}^{T}(\mathbf{X} \beta-y)+\frac{\lambda}{2} \operatorname{sign}(\beta)\right)_{l} \tag{20}
\end{equation*}
$$

and requires one to solve

$$
\begin{equation*}
\mathbf{X}^{T} \mathbf{y}=\mathbf{X}^{T} \mathbf{X} \beta^{*}+\frac{\lambda}{2} \operatorname{sign}\left(\beta^{*}\right) \tag{21}
\end{equation*}
$$

No close analytical solution for $\beta^{*}$ exists for this equation, and only numerical solution can be found.

### 1.0.2 Simple linear regression model using scikit-learn

We start with comparing our linear regression results with those of Scikit-Learn library.
To demonstrate capabilities, we will solve the problem of nuclear binding energies.
A popular and physically intuitive model which can be used to parametrize the experimental binding energies of all nucleai in periodic table is the so-called liquid drop model. The ansatz is based on the following expression

$$
B E(N, Z)=a_{1} A-a_{2} A^{2 / 3}-a_{3} \frac{Z^{2}}{A^{1 / 3}}-a_{4} \frac{(N-Z)^{2}}{A}
$$

where $A$ stands for the number of nucleons and the $a_{i}$ s are parameters which are determined by a fit to the experimental data.

To arrive at the above expression we have assumed that we can make the following assumptions:

- There is a volume term $a_{1} A$ proportional with the number of nucleons (the energy is also an extensive quantity). When an assembly of nucleons of the same size is packed together into the smallest volume, each interior nucleon has a certain number of other nucleons in contact with it. This contribution is proportional to the volume.
- There is a surface energy term $a_{2} A^{2 / 3}$. The assumption here is that a nucleon at the surface of a nucleus interacts with fewer other nucleons than one in the interior of the nucleus and hence its binding energy is less. This surface energy term takes that into account and is therefore negative and is proportional to the surface area.
- There is a Coulomb energy term $a_{3} \frac{Z^{2}}{A^{1 / 3}}$. The electric repulsion between each pair of protons in a nucleus yields less binding.
- There is an asymmetry term $a_{4} \frac{(N-Z)^{2}}{A}$. This term is associated with the Pauli exclusion principle and reflects the fact that the proton-neutron interaction is more attractive on the average than the neutron-neutron and proton-proton interactions.

We will fit the binding energy $B E$ as a function of $A$ with functions $g_{0}(x)=1, g_{1}(x)=x$, $g_{2}(x)=x^{2 / 3}, g_{3}(x)=x^{-1 / 3}, g_{4}(x)=1 / x$.

The binding energies are in file "NucleousEnergy.dat". The Python code follows here.
[3] :

```
# Binding energy in terms of nucleous weight A==x, is in this file
from numpy import *
from pylab import *
na_data = loadtxt('NucleousEnergy.dat').T
x,y = na_data
plot(x,y)
show()
```


[4]:

```
# Seeting up the Design matrix
X=zeros((len(x),5))
X[:,0]=1 # all functions we need
X[:,1]=x
X[:,2]=x**(2/3)
X[:,3]=x**(-1/3)
X[:,4]=1./x
```

[5]: from sklearn.linear_model import LinearRegression

```
# Using scikit to get coefficients
lg = LinearRegression()
clf=lg.fit(X,y)
yt=clf.predict(X) # widetilde(y)
```

This is an equivalent code, but using our own equations derived above.
[6]:

```
# matrix inversion to find beta
Beta = dot(linalg.inv(X.T @ X) @ X.T, y)
# and then make the prediction
ytilde = X @ Beta
```

[7]:

```
# comparing the regression with data and our regression with those from the
    \hookrightarrowlibrary
plot(x,yt,label='Regression library')
plot(x,y, label='Data')
plot(x,ytilde,label='Regression ours')
xlabel('A')
ylabel('Binding Energy')
legend(loc='best')
show()
```


[9] :

```
from sklearn.metrics import mean_squared_error, r2_score,\sqcup
    \iotamean_squared_log_error, mean_absolute_error
# more information from library
print('The intercept alpha: \n', lg.intercept_)
print('Coefficient beta : \n', lg.coef_)
print('Our coefficients: \n', Beta)
# The mean squared error
print("Mean squared error: %.2f" % mean_squared_error(y, yt))
```

```
# Explained variance score: 1 is perfect prediction
print('Variance score: %.2f' % r2_score(y, yt))
# Mean squared log error
print('Mean squared log error: %.2f' % mean_squared_log_error(y, yt) )
# Mean absolute error
print('Mean absolute error: %.2f' % mean_absolute_error(y, yt))
```

The intercept alpha:
5.294399745619717
Coefficient beta :
$[0.00000000 \mathrm{e}+00-2.96611194 \mathrm{e}-02 \quad 2.01719003 \mathrm{e}-01 \quad 1.08078025 \mathrm{e}+01$
-4.03097597e+01]
Our coefficients:
[ 5.29439975e+00 -2.96611194e-02 $2.01719003 \mathrm{e}-01 \quad 1.08078025 \mathrm{e}+01$
-4.03097597e+01]
Mean squared error: 0.02
Variance score: 0.95
Mean squared log error: 0.00
Mean absolute error: 0.05

The function meansquarederror gives us the mean square error, a risk metric corresponding to the expected value of the squared (quadratic) error or loss defined as

$$
\operatorname{MSE}(y, \tilde{y})=\frac{1}{n} \sum_{i=0}^{n-1}\left(y_{i}-\tilde{y}_{i}\right)^{2}
$$

This function is equivalent to the $\chi^{2}$ function defined above.
Another quantity is the mean absolute error (MAE), a risk metric corresponding to the expected value of the absolute error loss using l1-norm. The MAE is defined as follows

$$
\operatorname{MAE}(y, \tilde{y})=\frac{1}{n} \sum_{i=0}^{n-1}\left|y_{i}-\tilde{y}_{i}\right|
$$

We present the squared logarithmic (quadratic) error

$$
\operatorname{MSLE}(y, \tilde{y})=\frac{1}{n} \sum_{i=0}^{n-1}\left(\log _{e}\left(1+y_{i}\right)-\log _{e}\left(1+\tilde{y}_{i}\right)\right)^{2}
$$

where $\log _{e}(x)$ stands for the natural logarithm of $x$. This error estimate is best to use when targets having exponential growth, such as population counts, average sales of a commodity over a span of years etc.

Finally, another cost function is the Huber cost function used in robust regression.
The rationale behind this possible cost function is its reduced sensitivity to outliers in the data set. In our discussions on dimensionality reduction and normalization of data we will meet other ways of dealing with outliers.

### 1.0.3 Libraries

A useful Python package for data analysics is pandas, which is an open source library providing high-performance data structures and data analysis tools for Python. pandas stands for panel data, a term borrowed from econometrics.
pandas has two major classes, the DataFrame class with two-dimensional data objects and the class Series with a focus on one-dimensional data objects. Both classes allow you to index data easily as we will see in the examples below.
pandas allows you also to perform mathematical operations on the data, spanning from simple reshapings of vectors and matrices to statistical operations.

The following simple example shows how we can make tables of our data. Here we define a data set which includes names, place of birth and date of birth, and displays the data in an easy to read way.
[10]:

```
import pandas as pd
from IPython.display import display
data = {'First Name': ["Frodo", "Bilbo", "Aragorn II", "Samwise"],
    'Last Name': ["Baggins", "Baggins","Elessar","Gamgee"],
    'Place of birth': ["Shire", "Shire", "Eriador", "Shire"],
    'Date of Birth T.A.': [2968, 2890, 2931, 2980]
    }
data_pandas = pd.DataFrame(data)
display(data_pandas)
print('Standard Python print:', data)
```

|  | First Name | Last Name Place of birth | Date of Birth T.A. |  |
| :--- | ---: | ---: | ---: | ---: | ---: |
| 0 | Frodo | Baggins | Shire | 2968 |
| 1 | Bilbo | Baggins | Shire | 2890 |
| 2 | Aragorn II | Elessar | Eriador | 2931 |
| 3 | Samwise | Gamgee | Shire | 2980 |

Standard Python print: \{'First Name': ['Frodo', 'Bilbo', 'Aragorn II', 'Samwise'], 'Last Name': ['Baggins', 'Baggins', 'Elessar', 'Gamgee'], 'Place of birth': ['Shire', 'Shire', 'Eriador', 'Shire'], 'Date of Birth T.A.': [2968, 2890, 2931, 2980]\}

In the above we have imported pandas with the shorthand $\mathbf{p d}$, the latter has become the standard way we import pandas. We make then a list of various variables and reorganize the aboves lists into a DataFrame and then print out a neat table with specific column labels as Name, place of birth and date of birth. Displaying these results, we see that the indices are given by the default numbers from zero to three. pandas is extremely flexible and we can easily change the above indices by defining a new type of indexing as
[11]:

```
data_pandas = pd.DataFrame(data,index=['Frodo','Bilbo','Aragorn','Sam'])
display(data_pandas)
```

First Name Last Name Place of birth Date of Birth T.A.

| Frodo | Frodo | Baggins | Shire | 2968 |
| :--- | ---: | ---: | ---: | ---: |
| Bilbo | Bilbo | Baggins | Shire | 2890 |
| Aragorn | Aragorn II | Elessar | Eriador | 2931 |
| Sam | Samwise | Gamgee | Shire | 2980 |

Thereafter we display the content of the row which begins with the index Aragorn
[12]: display(data_pandas.loc['Aragorn'])

| First Name | Aragorn II |
| :--- | ---: |
| Last Name | Elessar |
| Place of birth | Eriador |
| Date of Birth T.A. | 2931 |

Name: Aragorn, dtype: object
We can easily append data to this, for example
[13]:

```
new_hobbit = {'First Name': ["Peregrin"],
    'Last Name': ["Took"],
    'Place of birth': ["Shire"],
    'Date of Birth T.A.': [2990]
        }
#data_pandas=data_pandas.append(pd.DataFrame(new_hobbit, index=['Pippin']))
data_pandas=pd.concat([data_pandas,pd.DataFrame(new_hobbit, index=['Pippin'])])
display(data_pandas)
```

|  | First Name | Last Name | Place of | birth | Date of Birth T.A. |
| :--- | ---: | ---: | ---: | ---: | ---: |
| Frodo | Frodo | Baggins | Shire | 2968 |  |
| Bilbo | Bilbo | Baggins | Shire | 2890 |  |
| Aragorn | Aragorn II | Elessar | Eriador | 2931 |  |
| Sam | Samwise | Gamgee | Shire | 2980 |  |
| Pippin | Peregrin | Took | Shire | 2990 |  |

Here are other examples where we use the DataFrame functionality to handle arrays, now with more interesting features for us, namely numbers. We set up a matrix of dimensionality $10 \times 5$ and compute the mean value and standard deviation of each column. Similarly, we can perform mathematical operations like squaring the matrix elements and many other operations.
[14]:

```
import numpy as np
import pandas as pd
from IPython.display import display
np.random.seed(100) # some arbitrary random seed to always start
    \iotathe same
# setting up a 10 x 5 matrix
rows = 10
cols = 5
a = np.random.randn(rows,cols) # normal distributed random numbers (10x5)
df = pd.DataFrame(a) # df is now panda DataFrame
```

```
display(df)
print(df.mean()) # easy to get mean of each column
our_mean = [sum(a[:,i])/rows for i in range(cols)]
print('our mean=', our_mean)
print(df.std()) # easy to get standard deviation
# Note that we have to use 1/(rows-1), which is more precise than 1/rows!
our_s = [ np.sqrt(sum((a[:,i]-our_mean[i])**2)/(rows-1)) for i in range(cols)]
print('our sigma=', our_s)
```

|  | 0 | 1 | 2 | 3 | 4 |
| ---: | ---: | ---: | ---: | ---: | ---: |
| 0 | -1.749765 | 0.342680 | 1.153036 | -0.252436 | 0.981321 |
| 1 | 0.514219 | 0.221180 | -1.070043 | -0.189496 | 0.255001 |
| 2 | -0.458027 | 0.435163 | -0.583595 | 0.816847 | 0.672721 |
| 3 | -0.104411 | -0.531280 | 1.029733 | -0.438136 | -1.118318 |
| 4 | 1.618982 | 1.541605 | -0.251879 | -0.842436 | 0.184519 |
| 5 | 0.937082 | 0.731000 | 1.361556 | -0.326238 | 0.055676 |
| 6 | 0.222400 | -1.443217 | -0.756352 | 0.816454 | 0.750445 |
| 7 | -0.455947 | 1.189622 | -1.690617 | -1.356399 | -1.232435 |
| 8 | -0.544439 | -0.668172 | 0.007315 | -0.612939 | 1.299748 |
| 9 | -1.733096 | -0.983310 | 0.357508 | -1.613579 | 1.470714 |

$0-0.175300$
10.083527
$2-0.044334$
3-0.399836
40.331939
dtype: float64
our mean= [-0.1753003003007798, 0.08352721390288316, -0.044333972284362075,
$-0.39983564919591685,0.33193916850842475$ ]

| 0 | 1.069584 |
| :--- | :--- |
| 1 | 0.965548 |
| 2 | 1.018232 |
| 3 | 0.793167 |
| 4 | 0.918992 |

dtype: float64
our sigma= [1.069584393754908, 0.9655479229776867, 1.0182315502230195,
$0.7931668855918225,0.918992356527374]$

Thereafter we can select specific columns only and plot final results
[15] :

```
df.columns = ['First', 'Second', 'Third', 'Fourth', 'Fifth']
df.index = np.arange(1,11)
display(df)
print('<Second>=', df['Second'].mean() )
print('Info of DataFrame=', df.info())
```

| print(df.describe()) |  |  |  |  |  |
| :--- | ---: | ---: | ---: | ---: | ---: |
|  | First | Second | Third | Fourth | Fifth |
| 1 | -1.749765 | 0.342680 | 1.153036 | -0.252436 | 0.981321 |
| 2 | 0.514219 | 0.221180 | -1.070043 | -0.189496 | 0.255001 |
| 3 | -0.458027 | 0.435163 | -0.583595 | 0.816847 | 0.672721 |
| 4 | -0.104411 | -0.531280 | 1.029733 | -0.438136 | -1.118318 |
| 5 | 1.618982 | 1.541605 | -0.251879 | -0.842436 | 0.184519 |
| 6 | 0.937082 | 0.731000 | 1.361556 | -0.326238 | 0.055676 |
| 7 | 0.222400 | -1.443217 | -0.756352 | 0.816454 | 0.750445 |
| 8 | -0.455947 | 1.189622 | -1.690617 | -1.356399 | -1.232435 |
| 9 | -0.544439 | -0.668172 | 0.007315 | -0.612939 | 1.299748 |
| 10 | -1.733096 | -0.983310 | 0.357508 | -1.613579 | 1.470714 |

<Second>= 0.08352721390288316 <class 'pandas.core.frame.DataFrame'> Int64Index: 10 entries, 1 to 10 Data columns (total 5 columns):

| \# | Column | Non-Null Count | Dtype |
| :---: | :--- | :--- | :--- |
| --- | ----- | -------------- | ---- |
| 0 | First | 10 non-null | float64 |
| 1 | Second | 10 non-null | float64 |
| 2 | Third | 10 non-null | float64 |
| 3 | Fourth | 10 non-null | float64 |
| 4 | Fifth | 10 non-null | float64 |

dtypes: float64(5)
memory usage: 480.0 bytes
Info of DataFrame= None

|  | First | Second | Third | Fourth | Fifth |
| :--- | ---: | ---: | ---: | ---: | ---: |
| count | 10.000000 | 10.000000 | 10.000000 | 10.000000 | 10.000000 |
| mean | -0.175300 | 0.083527 | -0.044334 | -0.399836 | 0.331939 |
| std | 1.069584 | 0.965548 | 1.018232 | 0.793167 | 0.918992 |
| min | -1.749765 | -1.443217 | -1.690617 | -1.613579 | -1.232435 |
| $25 \%$ | -0.522836 | -0.633949 | -0.713163 | -0.785061 | 0.087887 |
| $50 \%$ | -0.280179 | 0.281930 | -0.122282 | -0.382187 | 0.463861 |
| $75 \%$ | 0.441264 | 0.657041 | 0.861676 | -0.205231 | 0.923602 |
| $\max$ | 1.618982 | 1.541605 | 1.361556 | 0.816847 | 1.470714 |

[16]:

```
from pylab import plt, mpl
mpl.rcParams['font.family'] = 'serif'
    #usual type plotting
plt.plot(df.cumsum(), lw=2.0)
    #using pandas makes it easier
df.cumsum().plot(lw=2.0, figsize=(10,6))
plt.show()
```

\#using bars
df.plot.bar(figsize=(10,6), rot=15)
plt.show()




Example of a nice print of $4 \times 4$ matrix
[17]:

```
b = np.arange(16).reshape((4,4))
print(b)
df1 = pd.DataFrame(b)
print(df1)
```

[ $\left[\begin{array}{llll}0 & 1 & 2 & 3\end{array}\right]$
$\left[\begin{array}{llll}4 & 5 & 6 & 7\end{array}\right]$
$\left[\begin{array}{llll}8 & 9 & 10 & 11\end{array}\right]$
$\left[\begin{array}{llll}12 & 13 & 14 & 15\end{array}\right]$

|  | 0 | 1 | 2 | 3 |
| ---: | ---: | ---: | ---: | ---: |
| 0 | 0 | 1 | 2 | 3 |
| 1 | 4 | 5 | 6 | 7 |
| 2 | 8 | 9 | 10 | 11 |
| 3 | 12 | 13 | 14 | 15 |

and many other operations.
The Series class is another important class included in pandas. You can view it as a specialization of DataFrame but where we have just a single column of data. It shares many of the same features as _DataFrame. As with DataFrame, most operations are vectorized, achieving thereby a high performance when dealing with computations of arrays, in particular labeled arrays. As we will see below it leads also to a very concice code close to the mathematical operations we may be interested in. For multidimensional arrays, we recommend strongly xarray. xarray has much of the same flexibility as pandas, but allows for the extension to higher dimensions than two.
[ ]: $\square$

